

Knowledge-based rapid prototyping

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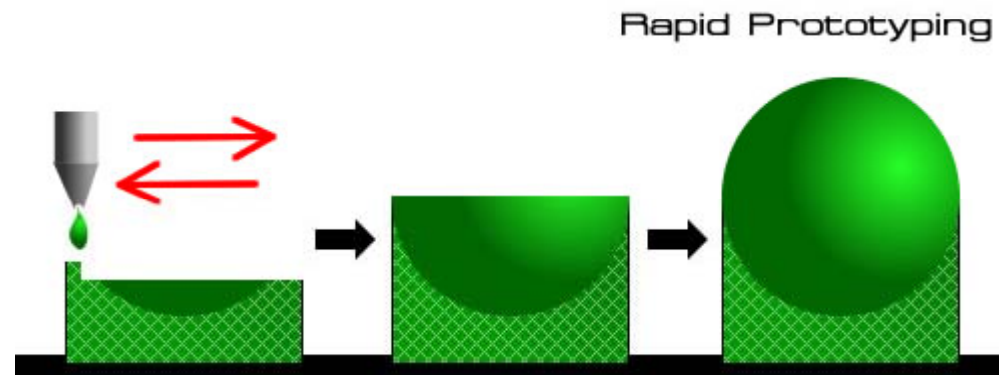
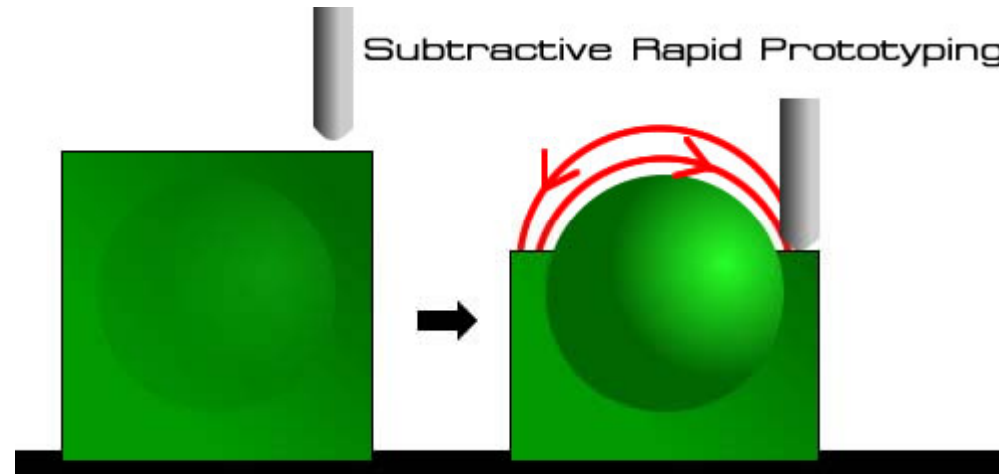
- Rapid technologies (RTs) are solutions that enable us to fulfil shape-intensive manufacturing expectations:
 - Reduce costs while increasing speed and accuracy
 - Physical realisation of products well before full-scale manufacturing
 - Improve quality
- **Two basic characteristics of RTs:**
 - Independence from the shape of the object to be manufactured
 - Dependence on physical principles, materials and target applications



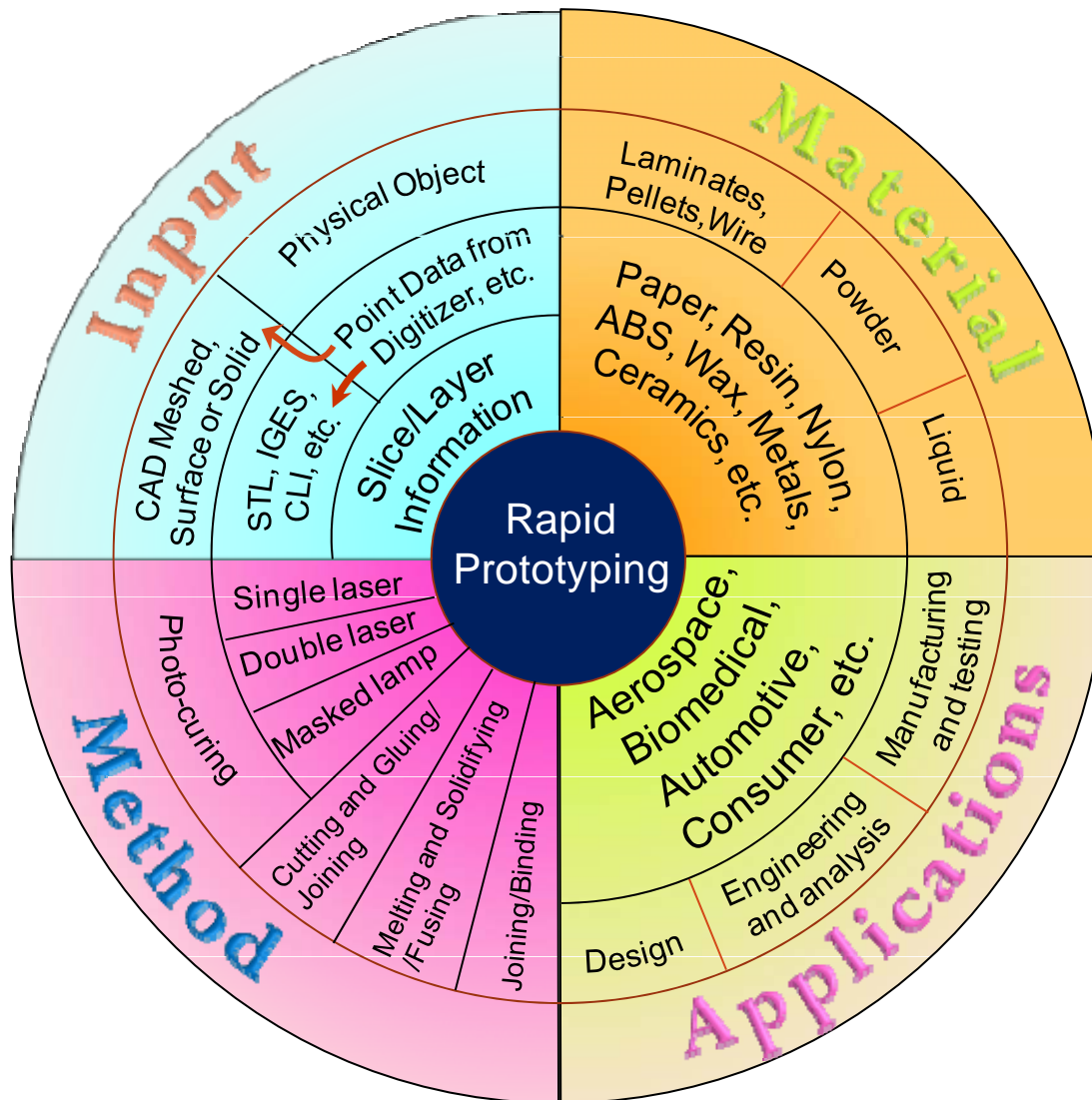
Quin Lamp

Photo courtesy Bathsheba Grossman

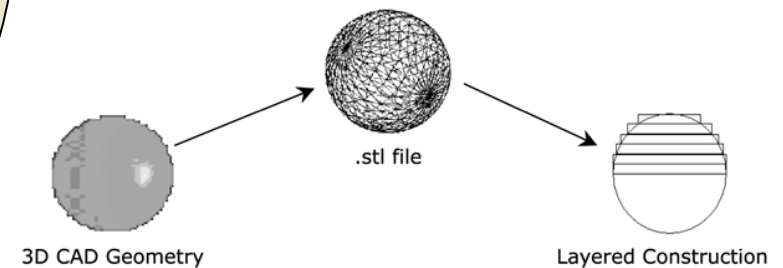
Categories of Rapid Technologies



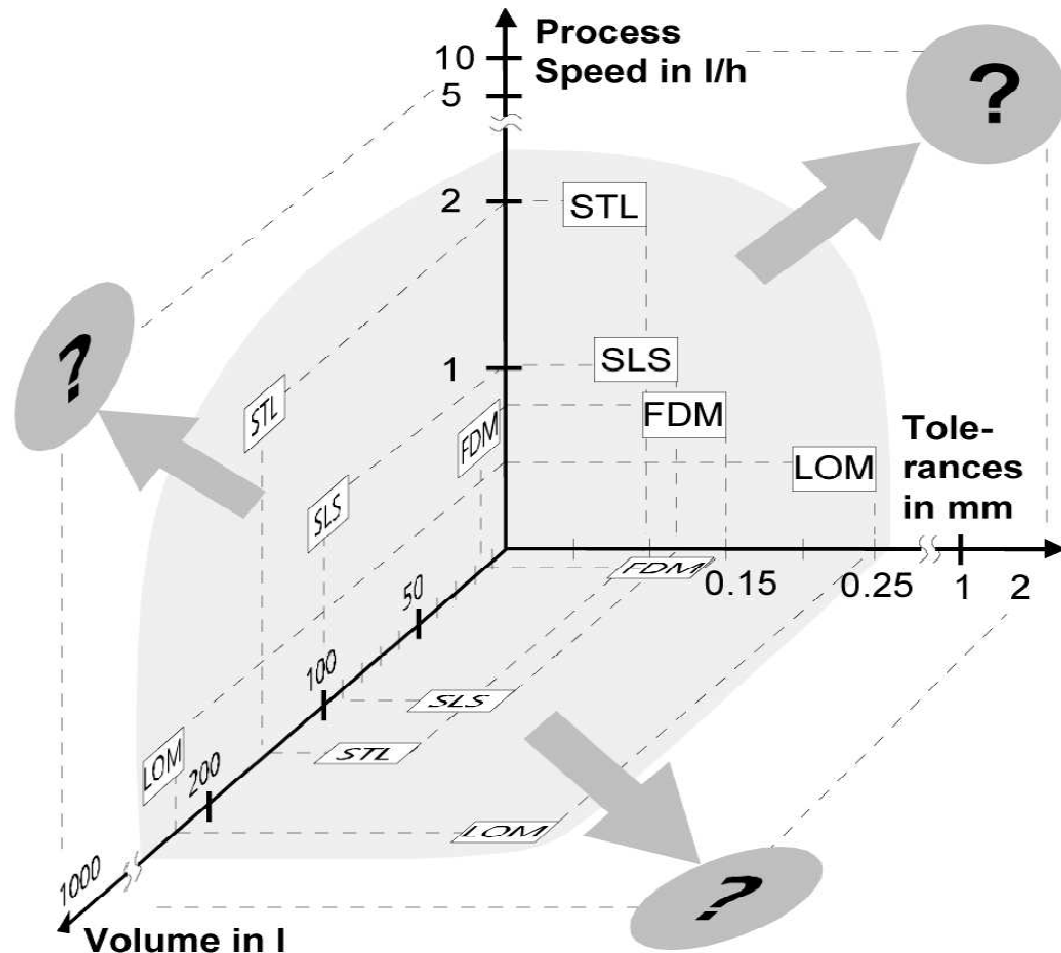
Rapid prototyping fundamentals



- Input
 - 3D model
 - Scanned data
 - › CMM
 - › Laser
 - › CT



RP Capabilities and Applications



Legend:

STL Stereolithography
SLS Selective Laser Sintering
LOM Laminated Object Manufacturing
FDM Fused Deposition Modelling

Volume scale unit:
1 l = 1 Litre = 10^{-3} m^3

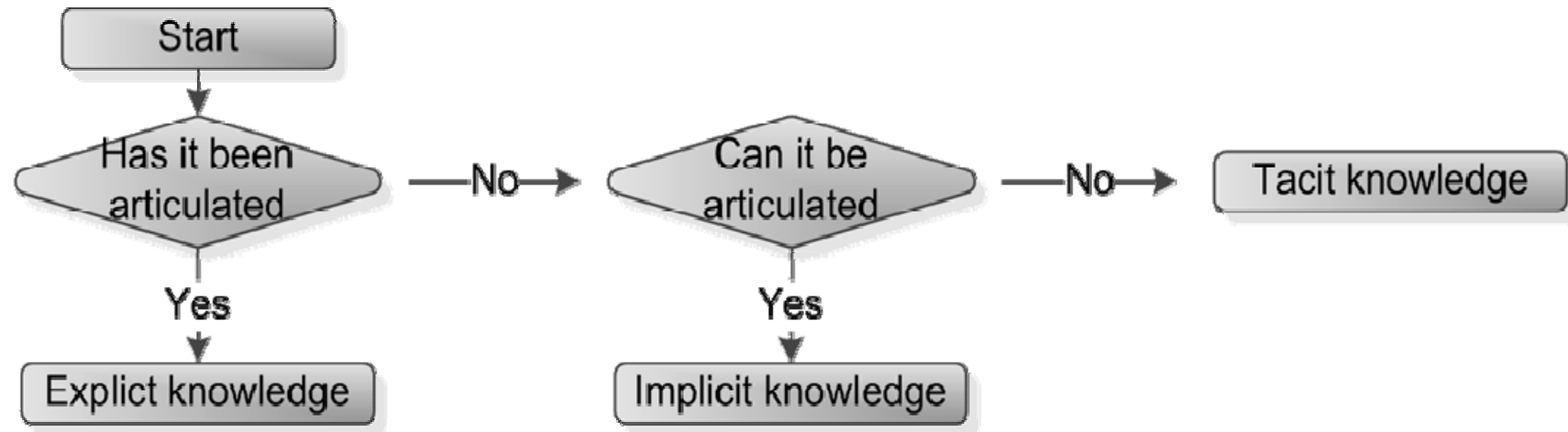


Diverse range of RTs supports:

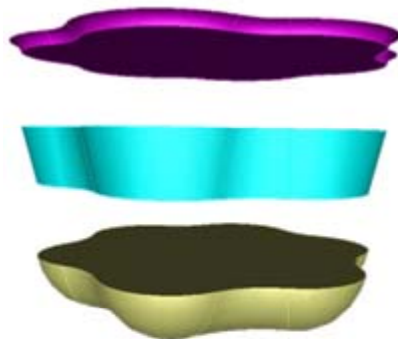
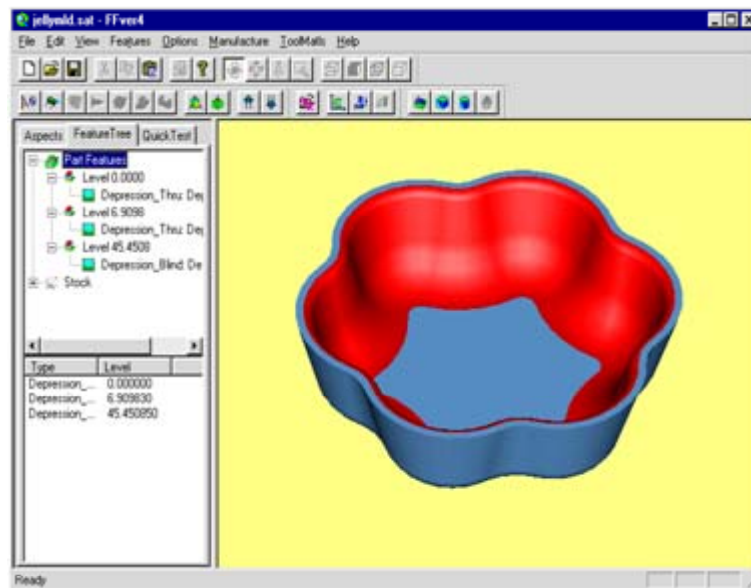
- Significant design freedom based on their ability selectively to remove, deposit or form materials



- Manufacturing is moving from resource-based to knowledge-based
- Knowledge content of manufactured products about 5% in 1945
- Today it's about 16%
- EU target by 2020 - at least 20%.



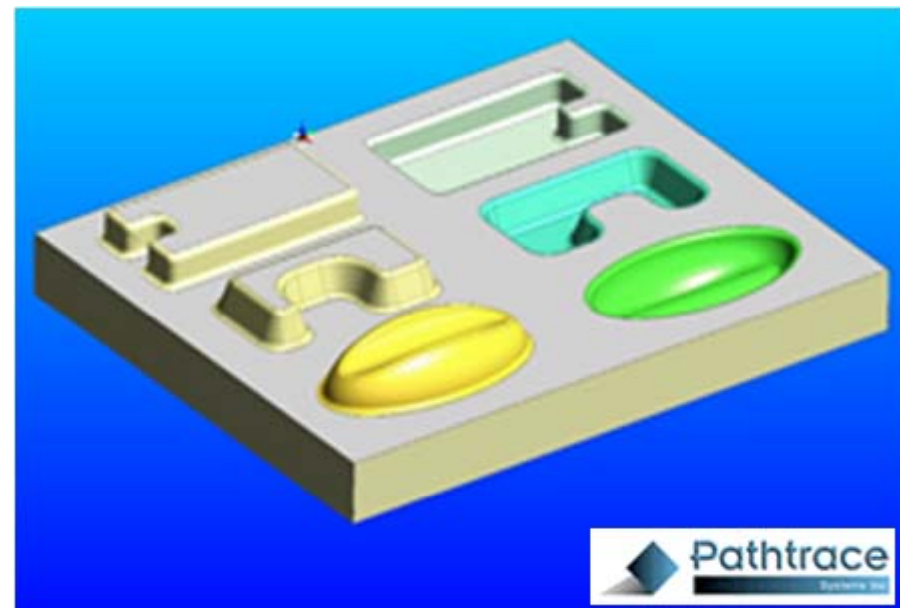
- To optimize specific production resources and processes;
- Transfer captured knowledge via knowledge platforms and competence networks to other areas where it can be employed to advantage.
- Knowledge as a 'product' is becoming more important to many SMEs constituting the great majority of the manufacturing enterprise pool.



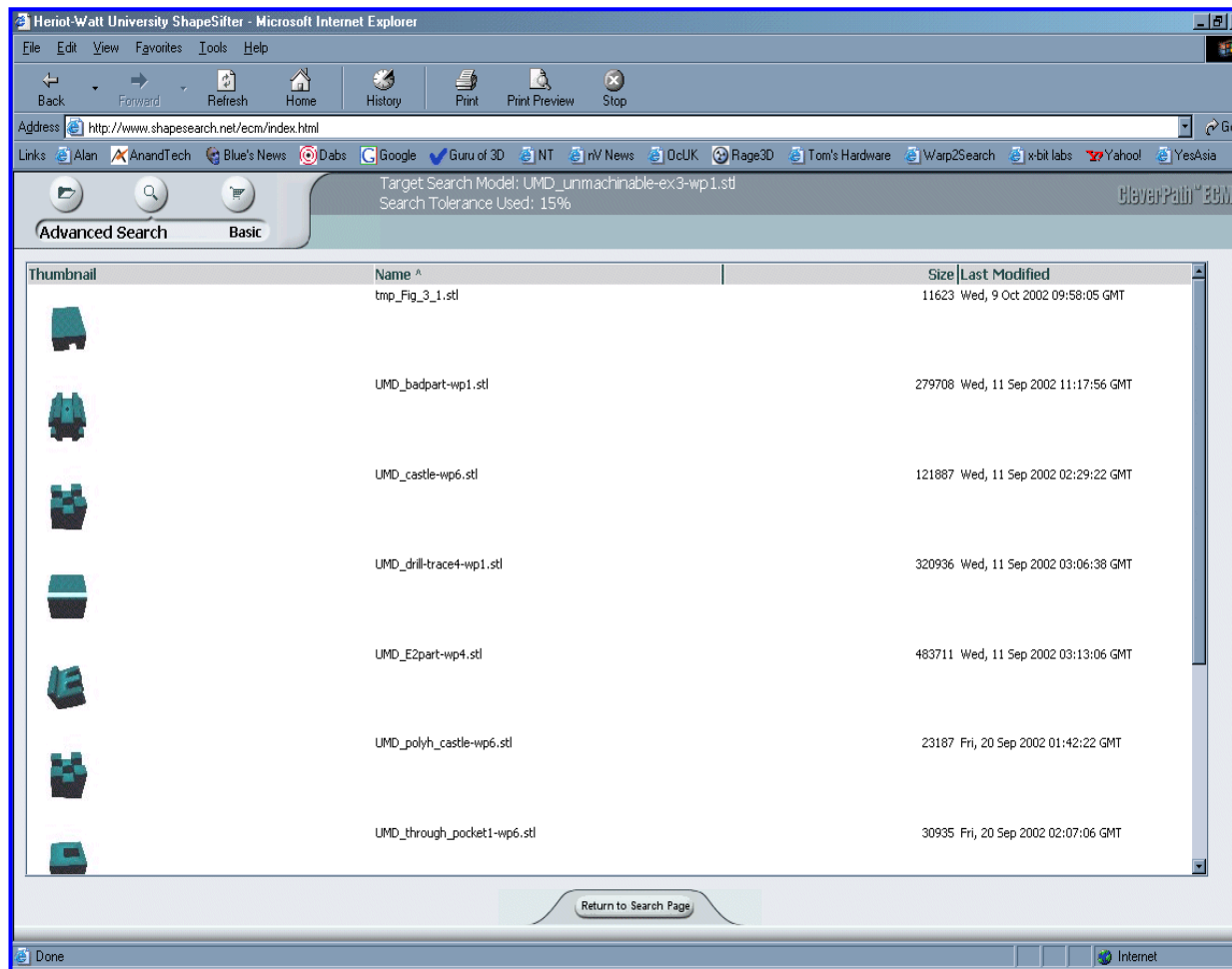
Heriot-Watt Feature Finder

Automatic feature finding

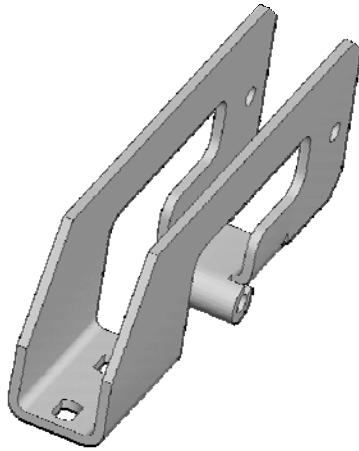
EdgeCAM Solid Machinist uses automatic feature recognition to interrogate the solid model to find **machinable features**. This information is then used to select the correct tools and to machine the features using EdgeCAM's extensive range of cutting strategies.



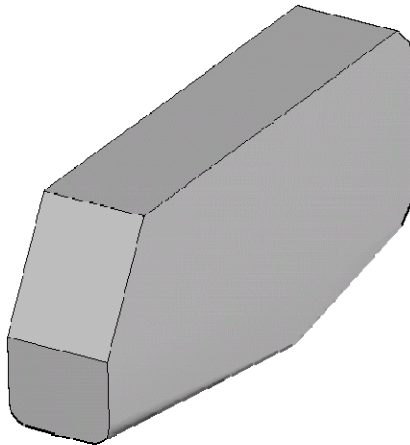
3D Part Search Engine



<http://www.partbrowser.com/>



Model



Convex Hull

Model Searching Parameters

- Hull Crumpliness
- Hull Packing
- Hull Compactness

$$H_{cp} = \frac{A_{\text{mod}}}{A_{\text{Hull}}}$$

$$H_p = 1 - \frac{V_{\text{mod}}}{V_{\text{Hull}}}$$

$$H_c = \frac{A_{\text{Hull}}^3}{V_{\text{Hull}}^2}$$

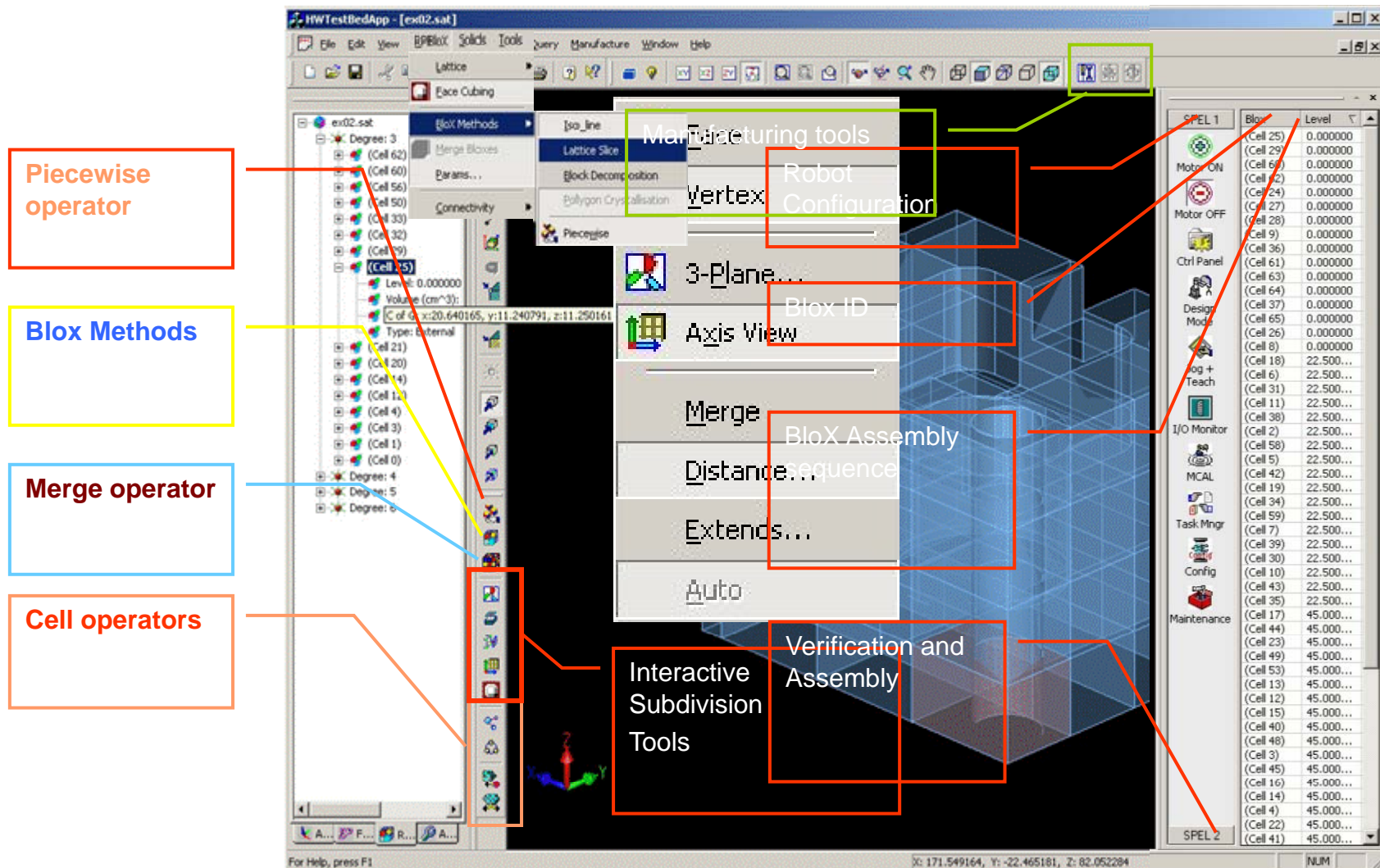
Search
tolerance

10%

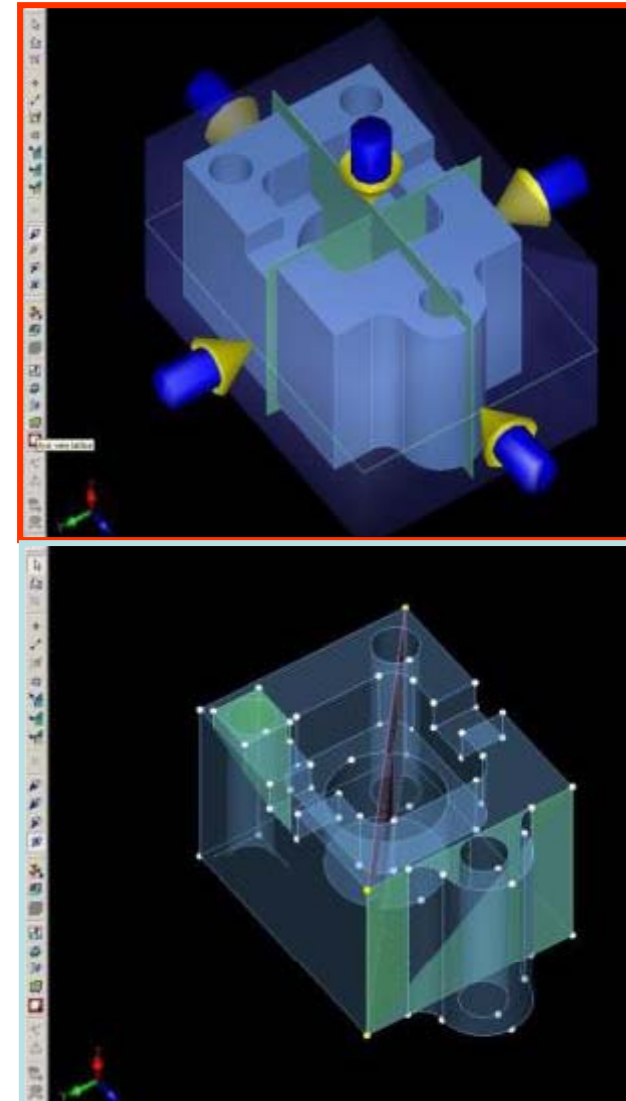
50%

25%

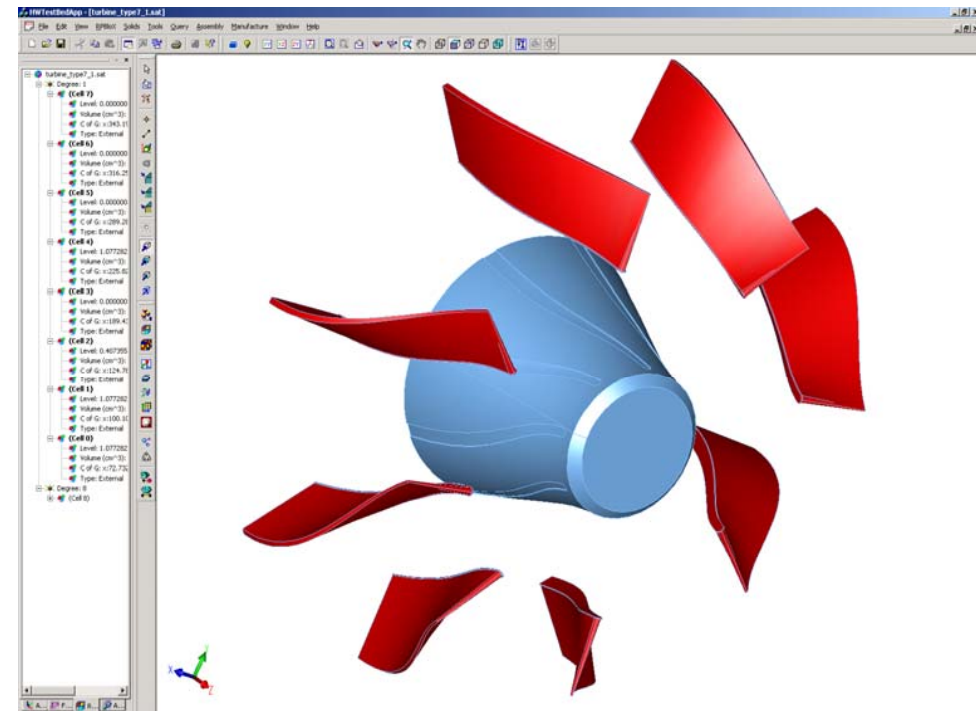
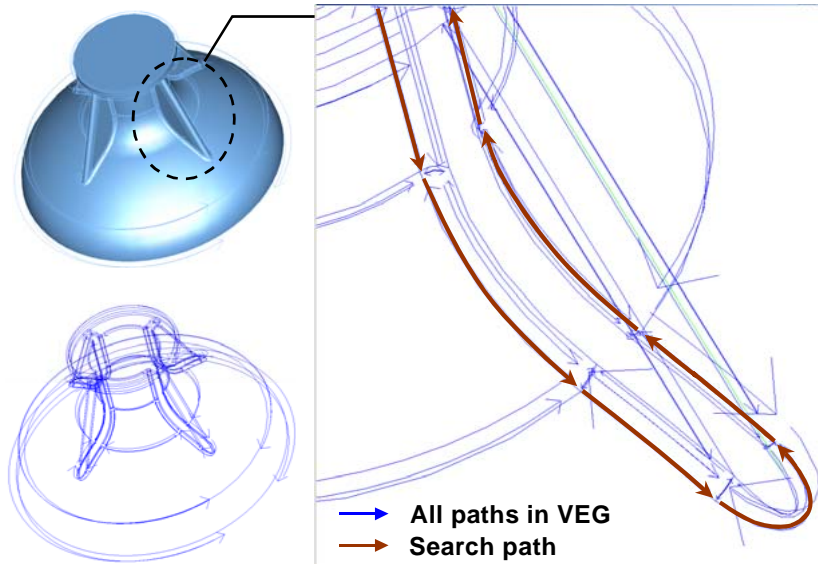
RPBloX TestBed



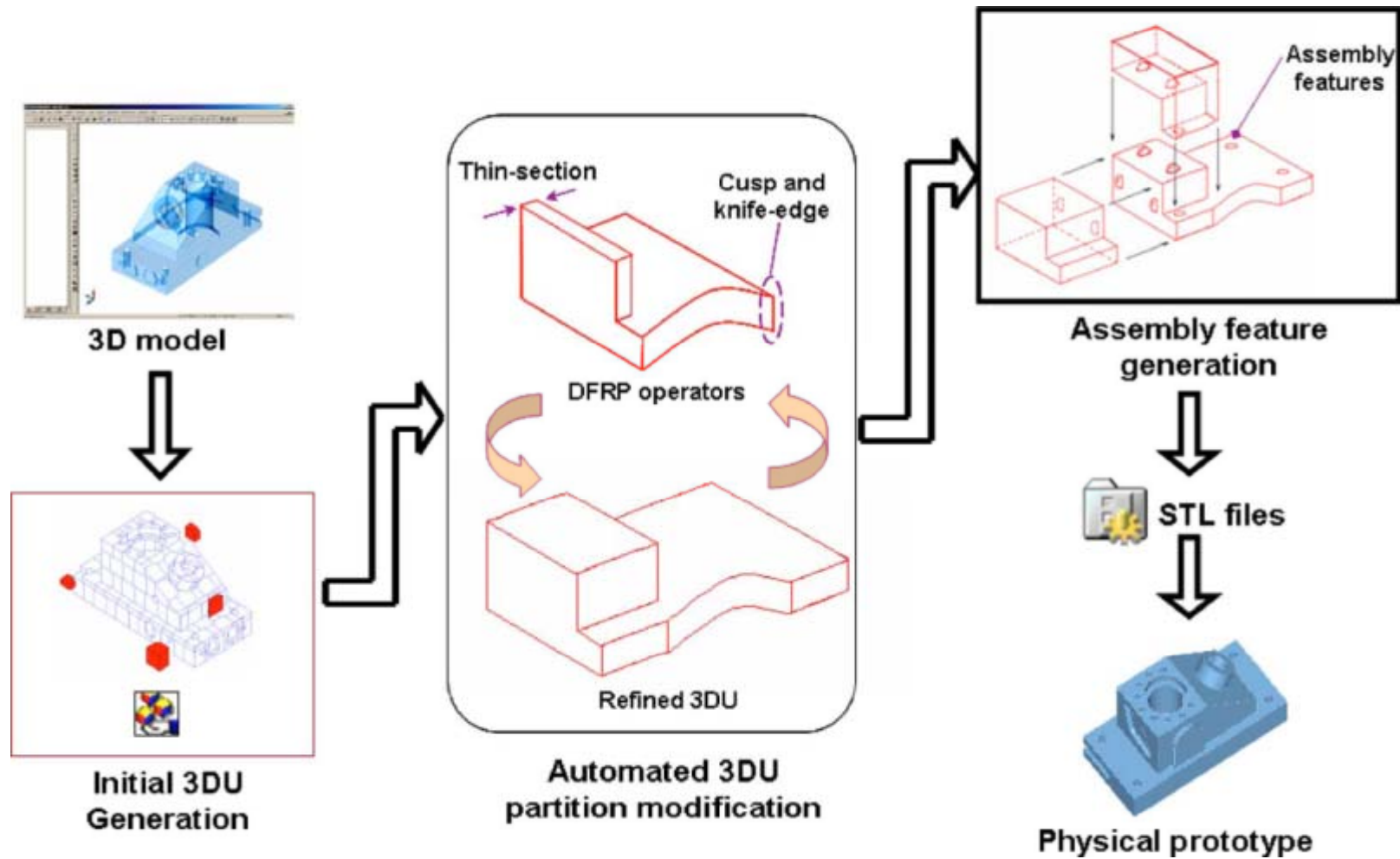
- ☐ Manual (Interactive)
- ☐ Uniform (Slicing Lattice)
- ☐ Block Decomposition (Face-bounding)
- ☐ Loop-based Decomposition
- ☐ Isoline Decomposition
- ☐ Pattern Decomposition



Subdivision of Freeform Solids using feature knowledge

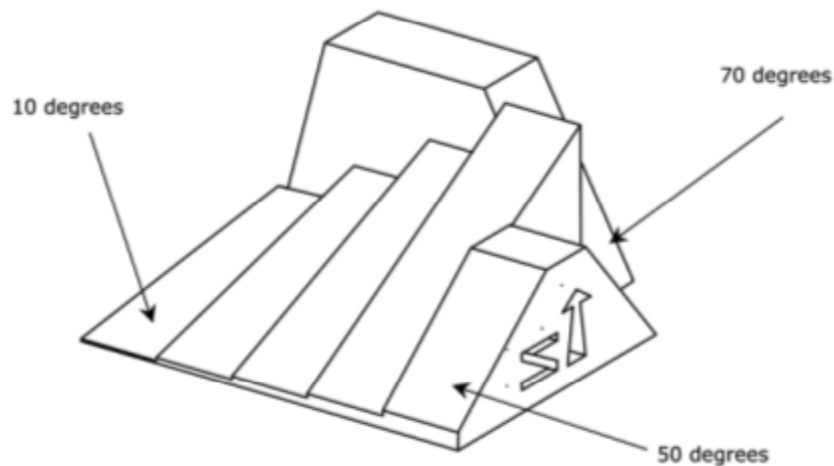


Model decomposition and Feature Recognition





Factors that affect the surface roughness of RP parts



RP surface roughness measurement test piece

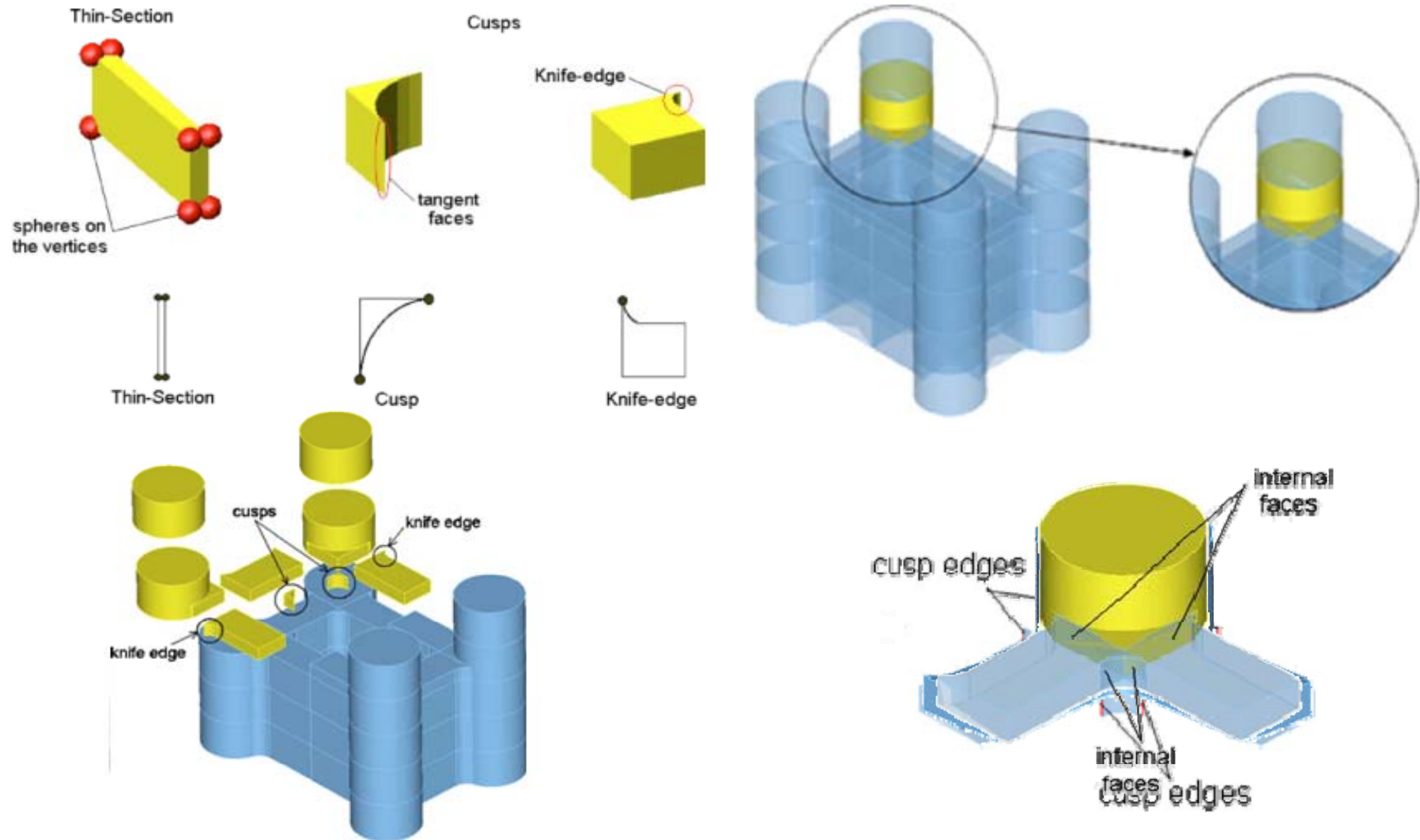
- Surface roughness
- Dimensional accuracy
- Mechanical properties

Technology – material	Layer thickness	Build angle, α /degrees				
		10	30	50	70	90
SLA – Epoxy (ACES style)	0.15	39.9	28.8	21.5	16.7	6.3
SLS – Polystyrene	0.20	65.2	35.6	32.6	24.7	20.6
SLS – Nylon	0.10	28.5	36.9	36.5	39.2	11.8
LOM – Paper	0.10	29.2	27.7	25.3	23.3	16.9
FDM – ABS	0.25	56.6	38.6	26.4	22.7	17.9

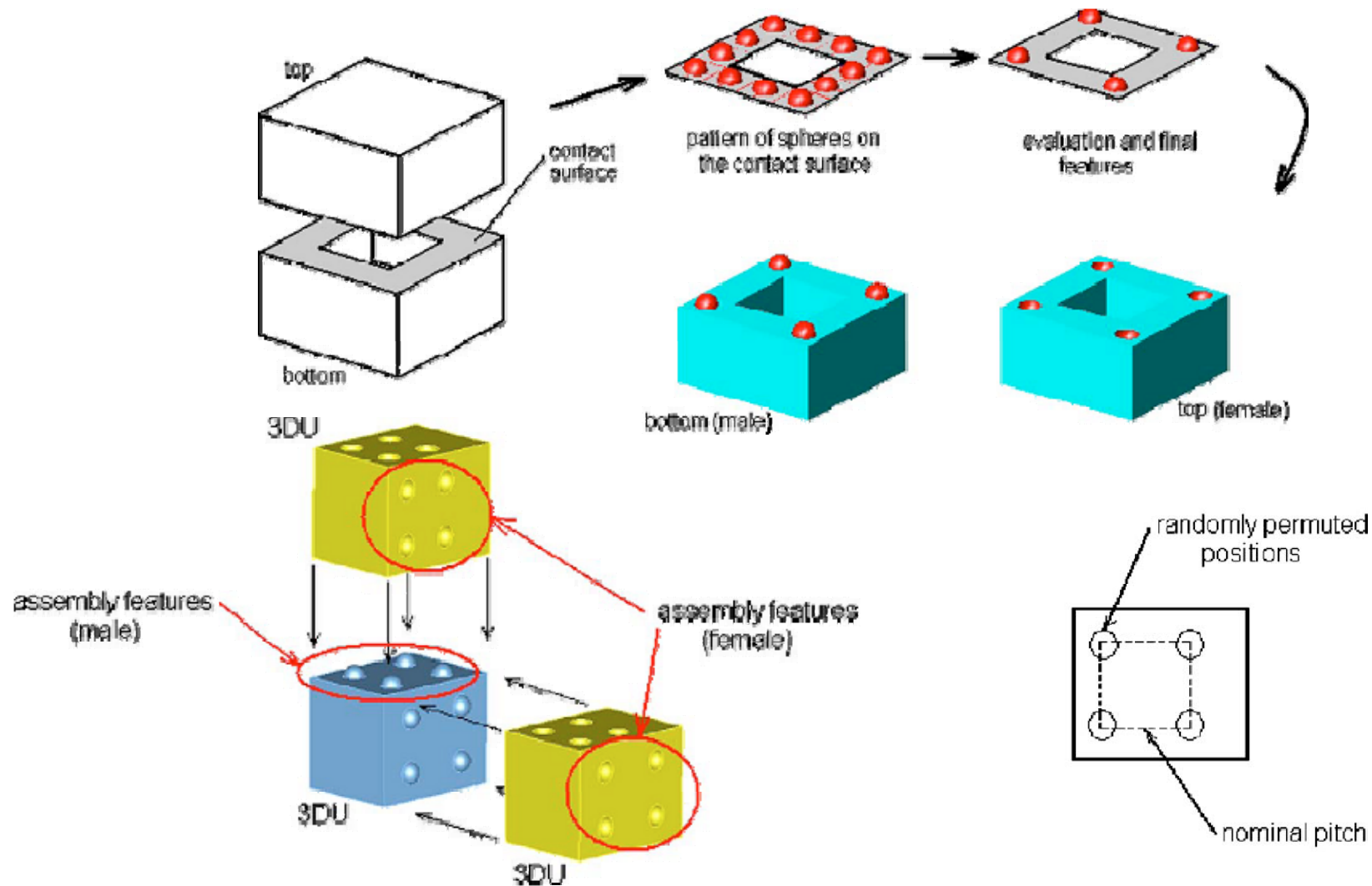
Surface roughness ($\mu\text{m Ra}$) for selected RP technologies

Technology – material	Intended dimensions from CAD model (mm)						
	34.50	50.35	52.50	56.00	60.00	71.00	75.00
	Actual dimensions of test parts (mm)						
SLA – Epoxy (ACES)	34.83	50.57	52.77	55.85	59.97	70.97	74.94
SLS – Polystyrene	34.43	50.45	52.62	56.48	60.14	71.31	75.12
SLS – Nylon	34.77	50.37	52.59	55.99	60.39	70.65	74.99
LOM – Paper	34.67	50.61	53.20	55.98	59.92	71.05	74.86
FDM – ABS	34.38	50.07	53.45	55.46	60.09	70.42	75.08

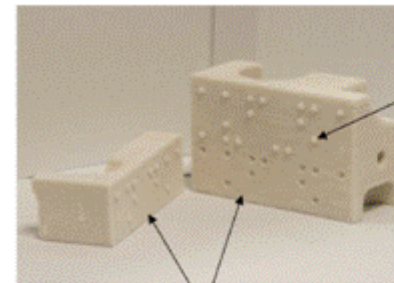
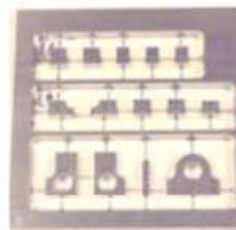
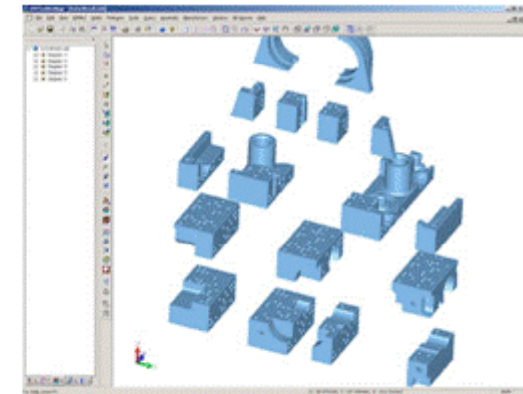
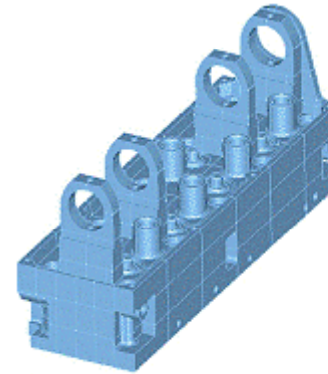
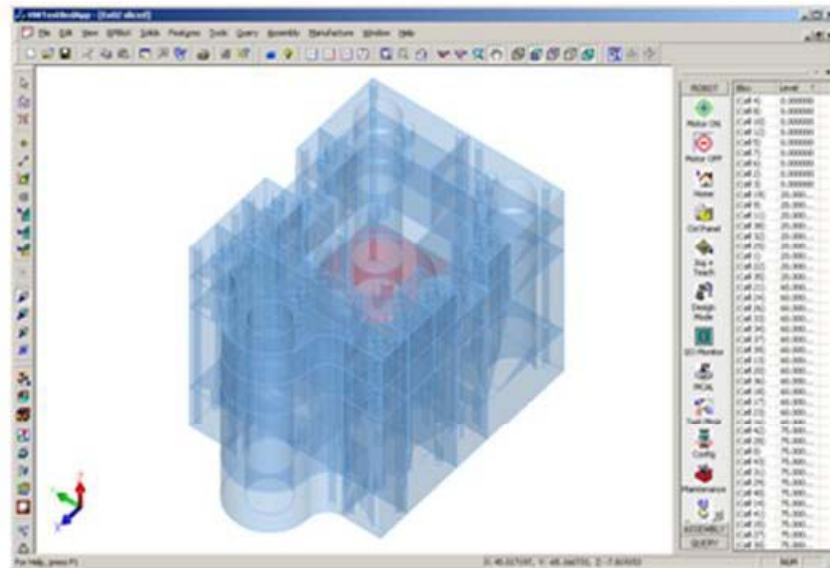
Linear dimensional accuracy of different RP technologies



DFMA (Assembly)

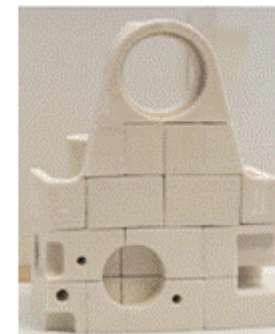


DFMA RPBloX - 3D Model in, Jigsaw out

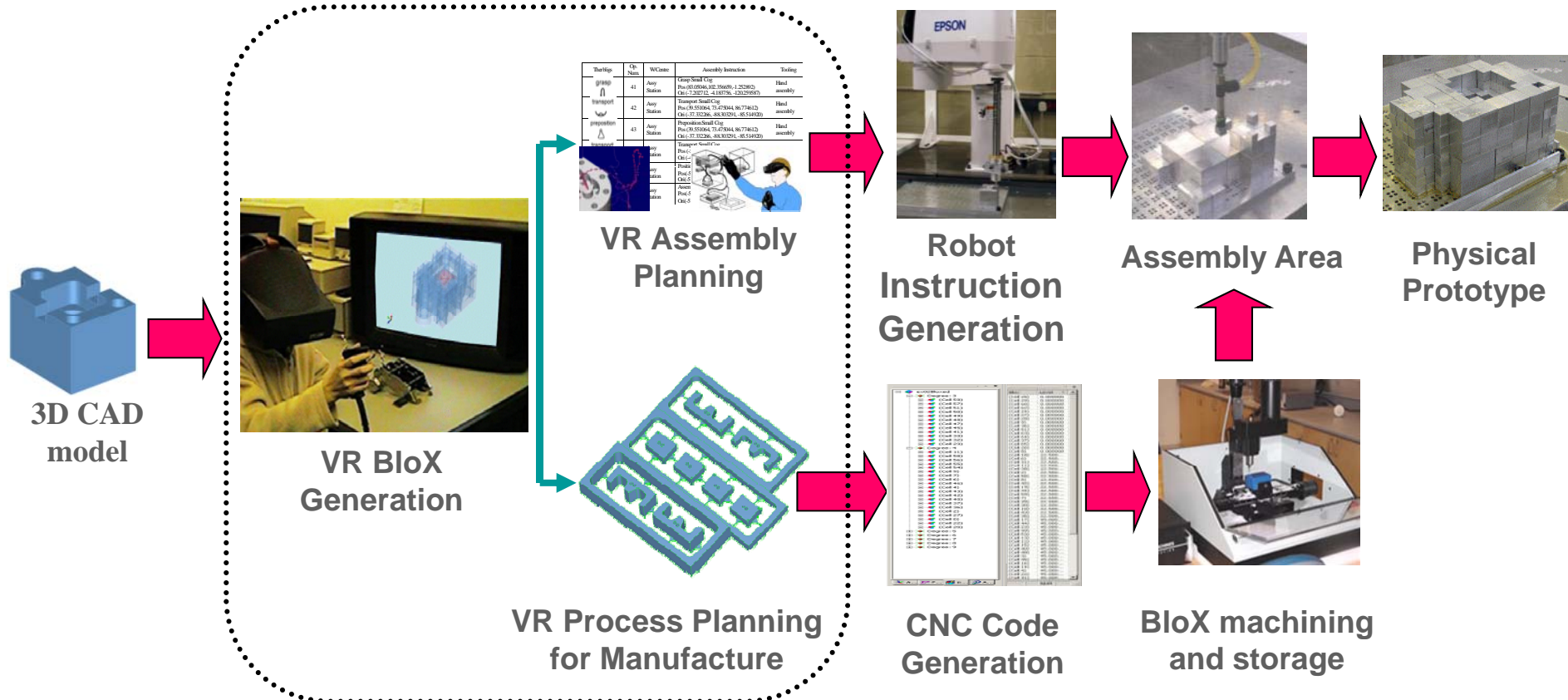


assembly
features

3DU's



VARP Interface

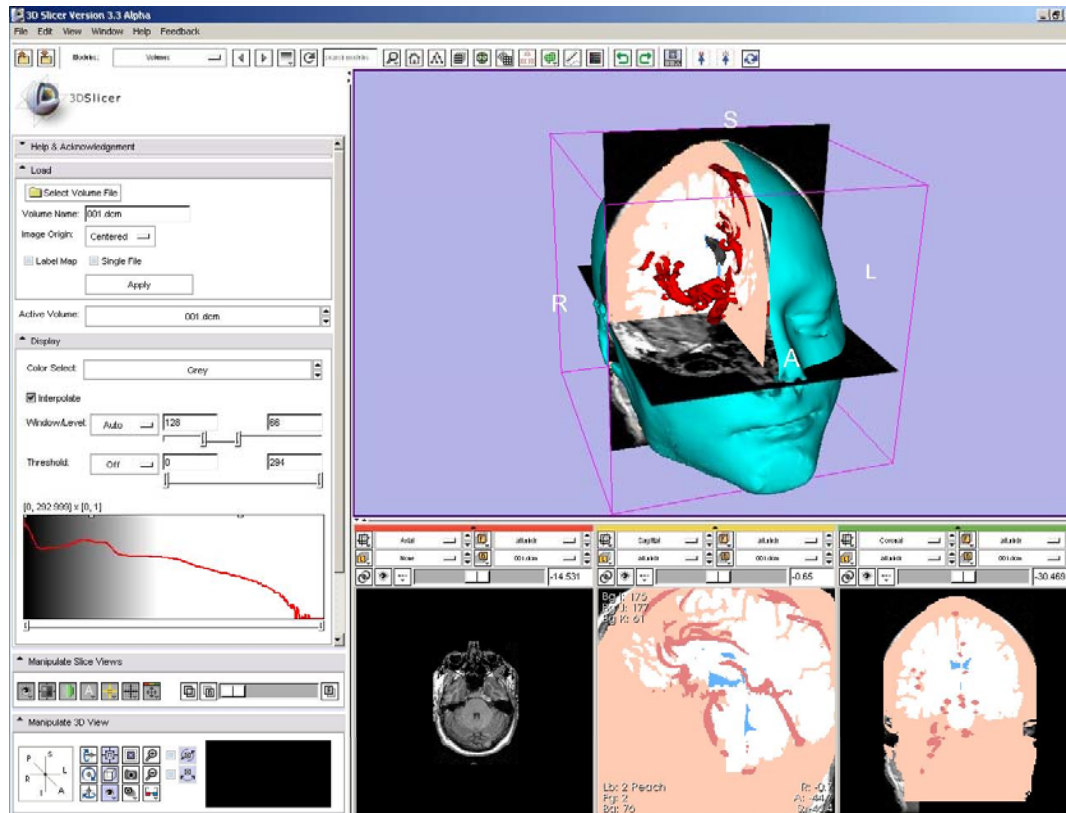


- RP-based fabrication has been used in the following medical applications:
 - Surgical and diagnostic aids
 - Prosthetics and medical product development
 - Manufacturing
 - Tissue Engineering

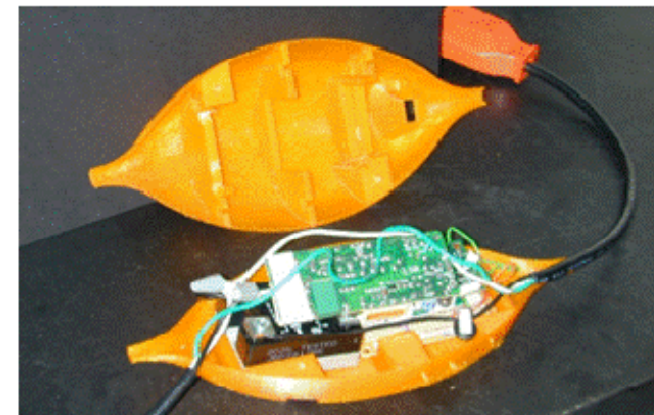
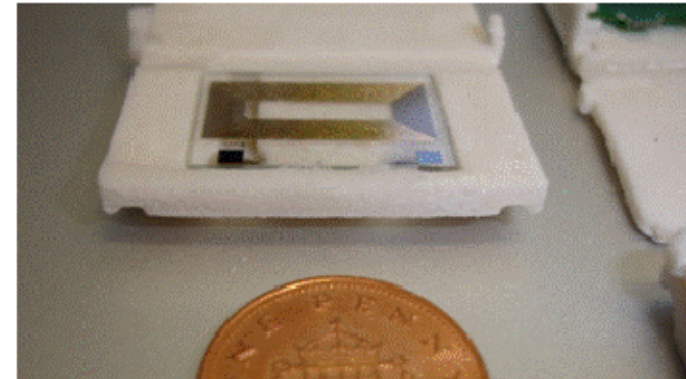


Due to the complex, organic nature of the product, RP technology was the most effective means of realizing these models.

Surgical and diagnostic aids



RP Validation

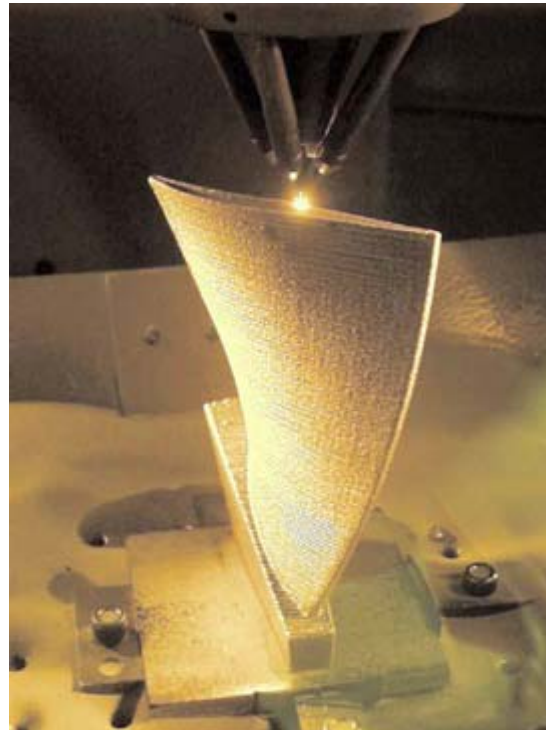




Direct AIM™



DSM Somos® NanoTool™



**Laser Engineering Net Shaping
(LENS)**



Direct Metal Deposition™ (DMD)

- ❖ **Speed:** *RP models can take a day or even longer to create.*
- ❖ **Cost:** *Using RP models to solve manufacturing problems is economical in high-volume productions.*
- ❖ **Accuracy:** *Very high precision RP is still not available.*
- ❖ **Materials:** *Only a few RP materials are classified as safe for transport into the operating room and none are currently safe for insertion inside the body.*
- ❖ **Ease of Use:** *RP machines generally require a degree of technical expertise to achieve good quality models.*

- A dominant technology for producing physical models for testing and evaluation purposes has been RP.
- Traps
 - Trial & Error may replace analysis
 - Design-for-Manufacturing may be overlooked
- Application of design and knowledge engineering in RP enables better manufacturability and dis/assemblability.
- Most of the problems regarding industry acceptance to RP are procedural rather than technical issues.
- A concerted effort to convince/educate industry of the value that RP offers will advance their usage.
- R&D related to RTs can be viewed in terms of four interconnected fields: processes, materials, machines and controls.