



# Picosecond Laser Machining of Optical Fibre Based Cantilever Sensors

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Picosecond-laser manufacturing of cantilever fibre optics sensing devices



- Introduction
  - Fibre sensing
  - Cantilevers
  - Picosecond laser manufacturing
- Fibre cantilever design and operation
- Manufacturing setup and process
- Results





## Fibre optic sensing



Advantages of fibre sensing:

- Small (typ. Ø=125 μm)
- Temperature stability (up to 1000 °C in some applications)
- Long distance to analytical instruments
- Large variety of sensing possibilities
- High accuracy and no alignment needed (in our case)
- Good knowledge of fibre technology







#### Cantilevers



- Well known (AFM)
- Many application areas
  - Vibration
  - Acceleration
  - Force
  - ...
- Bio-medical applications enabled through coatings









Conventional cantilever interrogation:

- Piezo-resistive method
  - Constraint in some EMI environmen
- Optical beam deflection
  - Alignment is complicated

Optical fibre cantilever

- High accuracy and no alignment during fabrication
- Combining sensing and interrogation
- Enable applications in space constrained environments













	ns-laser	ps-laser	fs-laser	Focused Ion Beam
Heat affect zone	Large	small	small	N.A.
Ablation rate	very high	high	Low (limited by av. power)	lowest
Surface finish	cracking	scattering (R <sub>a</sub> ≈400nm)	scattering (R <sub>a</sub> ≈200nm)	Optical quality (R <sub>a</sub> <10nm)
Examples	100 μm a)	100 µm	100 µm	4 μm

a) Raluca A. Negres, Mary A. Norton, David A. Cross, and Christopher W. Carr Optics Express, Vol. 18, Issue 19, pp. 19966-19976 (2010)





## **Previous work**



- Previous work on fibre-top cantilever
  - Using FIB machining (very time consuming ~4h)
  - Femtosecond laser + etching (two processing steps ~1h)

(D Iannuzzi et al. "Carving fiber-top cantilevers with femtosecond laser micromachining",2008, J. Micromech. Microeng. 18 035005; D Iannuzzi et al, "Fibre-top cantilevers: design, fabrication and applications", 2007 Meas. Sci. Technol. 18 3247)







# Manufacturing setup







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- Cantilever less than 10 µm thickness
- No cracking in fibre and cantilever
- Optical or near optical quality of the surfaces
- Very good control over the wall angle
- Short machining time
- Scalability for industrial production



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 Low energy cracking in fibre at 6 µJ pulse energy



 High energy cracking in ridge at 16 µJ pulse energy









• Strong tapering angle prevents sensor operation



- Possible Solutions:
  - Optimization of laser parameters (correlation between pulse energy and tapering angle)
  - Goniometers for rotation by desired angle





# Laser machining a fibre

- Wall angle depending on pulse energy
- Cracking at to high energy
- Cracking deeper inside fibre with to low energy
- Find energy for lowest cracking
- Correct for wall angle







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## Scheme of machining









## Scheme of machining











# Achieving parallel surfaces









• Without tilting the fibre

Tilted 8°

Tilted 12°



#### Second cut for parallel surfaces













## Problem with debris deposition

- 5µm thick layer of debris in centre
- Not removable with Ultrasonic bath
- Reduces signal





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### Second cut for parallel surfaces





- Central structure
  collects debris
- Only very small cut needed to remove









## Second cut for parallel surfaces

- All surfaces parallel
- Low debris deposition
- Repeatable with less than 10 µm thickness







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#### Actuation example







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- Cantilever structures out of fused silica fibre by ps-laser ablation
- Used as sensors for simple actuation experiments
- Stable results over 2.7  $\mu$ m actuation
- Accuracy of < 10 nm
- Manufacturing time for a cantilever < 1 min.
- Process easily adopts to mass manufacture





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